

Classical Mechanics
Phy 235, Lecture 10.

Frank L. H. Wolfs
 Department of Physics and Astronomy
 University of Rochester

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 1

1

A great way to start today.



PHOTO BY LABS.VELING.

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 2

2

Hamilton's Principle

"Of all the possible paths along which a dynamical system may move from one point to another within a specified time interval (consistent with any constraints), the actual path followed is that which minimizes the time integral of the difference between the kinetic and potential energies."

$$\delta \int_{t_1}^{t_2} (T - U) dt = 0$$

The quantity $T - U$ is called the **Lagrangian L** .

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 3

3

Lagrange Equation(s) of Motion.

$$\frac{\partial L}{\partial x_i} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) = 0$$

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 4

4

Generalized coordinates q_1, q_2, \dots

- Generalized coordinates are coordinates that completely specify the state of the system.
- Generalized coordinates do **not** need to be coordinates of a coordinate system.
- Hamilton's principle: *"Of all the possible paths along which a dynamical system may move from one point to another in configuration space within a specified time interval (consistent with any constraints), the actual path followed is that which minimizes the time integral of the Lagrangian function for the system."*

$$\delta \int_{t_1}^{t_2} L(q_i, \dot{q}_i, t) dt = 0$$

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 5

5

Problem 7.4

A particle moves in a plane under the influence of a force $f = -Ar^{\alpha-1}$ directed toward the origin; A and α are constants.

Choose appropriate generalized coordinates, and let the potential energy be zero at the origin.

- Find the Lagrangian equations of motion.
- Is the angular momentum about the origin conserved?
- Is the total energy conserved?

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 6

6



2 Minute 37 Second Intermission.

- Since paying attention for 1 hour and 15 minutes is hard when the topic is physics, let's take a 2 minute 37 second intermission.
- You can:
 - Stretch out.
 - Talk to your neighbors.
 - Ask me a quick question.
 - Enjoy the fantastic music.



Frank L. H. Wolfs

Department of Physics and Astronomy, University of Rochester, Slide 7

7

Problem 7.8

Consider a region of space divided by a plane. The potential energy of a particle in region 1 is U_1 and in region 2 it is U_2 . If a particle of mass m and with speed v_1 in region 1 passes from region 1 to region 2 such that its path in region 1 makes an angle θ_1 with the normal to the plane of separation and an angle θ_2 with the normal when in region 2, show that

$$\frac{\sin(\theta_1)}{\sin(\theta_2)} = \sqrt{1 + \frac{U_1 - U_2}{T_1}}$$

where $T_1 = (1/2)mv_1^2$.

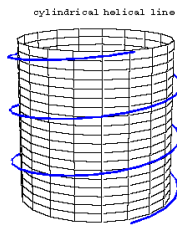
Frank L. H. Wolfs

Department of Physics and Astronomy, University of Rochester, Slide 8

8

Equations of Constraints

- One can remove the equations of constraint by a suitable choice of coordinates.
- For example, in the cylinder problem:
 - We can use three coordinates and one equation of constraint.
 - We can use two coordinates (azimuthal angle and vertical position) and no equations of constraint.



https://www.encyclopediaofmath.org/index.php/Helical_line

Frank L. H. Wolfs

Department of Physics and Astronomy, University of Rochester, Slide 9

9

Lagrange's Equations with Undetermined Multipliers.

- Assume constraints can be expressed in differential form:

$$\sum_{j=1}^s \frac{\partial f_k}{\partial q_j} dq_j = 0$$

- Constraints can be incorporated into the Lagrange equations:

$$\frac{\partial L}{\partial q_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} + \sum_{k=1}^m \lambda_k(t) \frac{\partial f_k}{\partial q_i} = 0$$

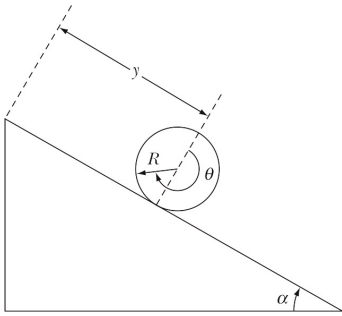
- The forces of constraint can be determined from the equations of constraint and the Lagrange multipliers:

$$Q_j = \sum_{k=1}^m \lambda_k(t) \frac{\partial f_k}{\partial q_j}$$

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 10

10

Example 7.9



Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 11

11

Problem 7.12

A particle of mass m rests on a smooth plane.

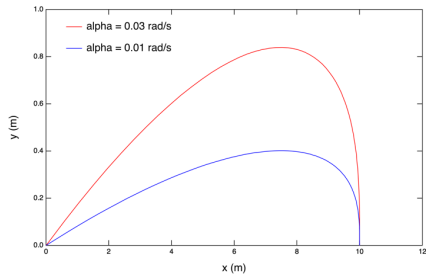
The plane is raised to an inclination angle θ at a constant rate α ($\theta = 0^\circ$ at $t = 0$ s), causing the particle to move down the plane.

Determine the motion of the particle.

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 12

12

Problem 7.12



Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 13

13

ENOUGH FOR TODAY?

Frank L. H. Wolfs Department of Physics and Astronomy, University of Rochester, Slide 14

14
