

Outline

- **Damped and driven harmonic motion:**
 - Damped harmonic motion occurs when friction or drag forces are acting on the system. Energy is dissipated and the system will gradually come to rest.
 - Driven harmonic motion adds a driving force in order to compensate for damping losses.

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Solving Second-Order Differential Equations. Damped and driven.

- **General form:**

$$\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by = f(x)$$
 - If you find two linearly independent solutions, every other solution will be a linear combination of these two solutions.
 - The general solution has two constants, defined by the initial conditions.
- **Homogeneous equation:**
 - $f(x)$ is equal to 0.
- **Inhomogeneous equation:**
 - $f(x)$ is not equal to 0.

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Homogeneous Equation: $\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by = 0$

- **Three different scenarios:**
 - $a^2 > 4b$
 - $a^2 = 4b$
 - $a^2 < 4b$

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Inhomogeneous Equation: $\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by = f(x)$

- Suppose:

- v is a solution of the inhomogeneous equation.
- u is the general solution of the homogeneous equation.

- Then:

- $u + v$ is the general solution of the inhomogeneous equation.

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Homogeneous Equation

- Consider a damping force $-bv$ and a restoring force $-kx$. The equation of motion for such system is: $ma = -bv - kx$.

- This provides us with the homogeneous equation:

$$\frac{d^2x}{dt^2} + \frac{b}{m} \frac{dx}{dt} + \frac{k}{m} x = \frac{d^2x}{dt^2} + 2\beta \frac{dx}{dt} + \omega_0^2 x = 0$$

- Try the following solution: $x = e^{rt}$.
- This is a valid solution if $r^2 + 2\beta r + \omega_0^2 = 0$. This requires:

$$r = \frac{-2\beta \pm \sqrt{4\beta^2 - 4\omega_0^2}}{2} = -\beta \pm \sqrt{\beta^2 - \omega_0^2}$$

- Three different scenarios:

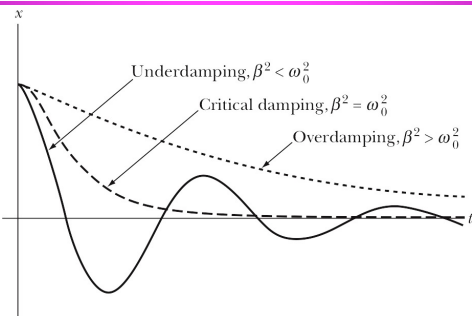
- $\beta^2 > \omega_0^2$: over damping. Two values of r .
- $\beta^2 = \omega_0^2$: critical damping. One value of r . Second solution is $te^{-\beta t}$.
- $\beta^2 < \omega_0^2$: under damping. Two values of r ; r is a complex number

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Damped motion.



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Numerical studies.

- Using tools such as VPython, it is easy to explore how damped harmonic motion changes as the damping conditions are changed.

- Let us have a look:

<https://www.glowscript.org/#/user/wolfs/folder/Public/program/Phy235-3D-DampedHarmonicMotion>

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Problem 3.22

- Let the initial position and speed of an overdamped, non-driven oscillator be x_0 and v_0 , respectively.
 - Determine the values of the amplitudes A_1 and A_2 in equation 3.44.

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3 Minute 12 Second Intermission.

- Since paying attention for 1 hour and 15 minutes is hard when the topic is physics, let's take a 3 minute 12 second intermission.

- You can:
 - Stretch out.
 - Talk to your neighbors.
 - Ask me a quick question.
 - Enjoy the fantastic music.



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Inhomogeneous Equation

- Consider a damping force $-bv$, a restoring force $-kx$, and a driving force $f(t)$. The equation of motion for such system is: $ma = -bv - kx + f(t)$.
- The equation of motion can be rewritten as:

$$\frac{d^2x}{dt^2} + \frac{b}{m} \frac{dx}{dt} + \frac{k}{m}x = \frac{d^2x}{dt^2} + 2\beta \frac{dx}{dt} + \omega_0^2 x = f(t)$$
- Suppose:
 - v is a solution of the inhomogeneous equation (this is called the **particular solution**).
 - u is the general solution of the homogeneous equation (this is called the **complementary solution**).
 then $u + v$ is the general solution of the inhomogeneous equation.

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Simplest case of driven harmonic motion.

- The simplest case of driven harmonic motion is the case when the driving force varies harmonically with time:

$$f(t) = F_0 \cos(\omega t)$$
- Important properties of the solution:
 - The complementary solution approaches 0 for large t .
 - The particular solution will have a frequency equal to the driving frequency.
 - The amplitude of the particular solution has a maximum when the driving frequency is equal to the resonance frequency:

$$\omega_R = \sqrt{\omega_0^2 - 2\beta^2}$$
 - The resonance frequency is less than the natural frequency when damping is present.

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Examples.

Driving frequency > damping frequency

(a)

Driving frequency < damping frequency

(b)

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Numerical studies.

- Using tools such as VPython, it is easy to explore how driven harmonic motion changes as the driving conditions are changed.

- Let us have a look:

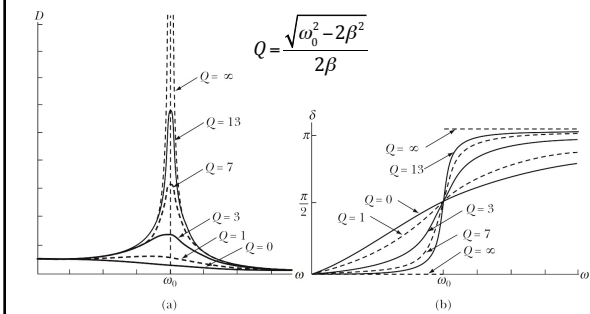
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Amplitude and phase angle for driven harmonic motion.



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Non-harmonic driving forces.

- Most driving forces are not pure harmonic driving forces.
- But every driving force can be written as a sum of pure harmonic functions (Fourier analysis).
- Consider that x_1 is the solution of the following equation:

$$\frac{d^2 x_1}{dt^2} + 2\beta \frac{dx_1}{dt} + \omega_0^2 x_1 = f_1(t)$$

- Consider that x_2 is the solution of the following equation:

$$\frac{d^2 x_2}{dt^2} + 2\beta \frac{dx_2}{dt} + \omega_0^2 x_2 = f_2(t)$$

- Then $x_1 + x_2$ is the solution of the following equation:

$$\frac{d^2 (x_1 + x_2)}{dt^2} + 2\beta \frac{d(x_1 + x_2)}{dt} + \omega_0^2 (x_1 + x_2) = f_1(t) + f_2(t)$$

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Non-harmonic driving forces.

- If the function F has a period τ , then we can write F as:

$$F(t) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} (a_n \cos(n\omega t) + b_n \sin(n\omega t))$$

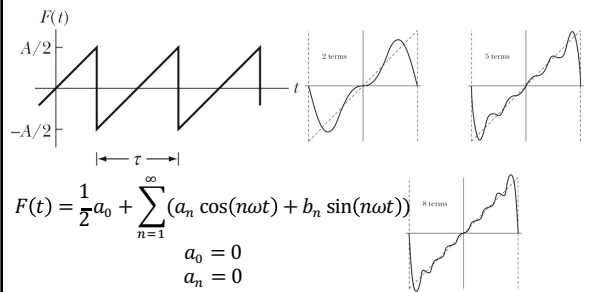
$$\omega = \frac{2\pi}{\tau}$$

- For each term in this series, we can find the solution to the corresponding inhomogeneous equation.
- The total solution is then the linear sum of all of these individual solutions.

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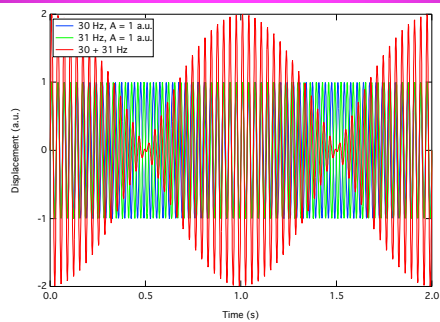
Example of Fourier Analysis.



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Adding harmonic functions.



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ENOUGH FOR TODAY?

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