### Physics 121, March 27, 2008. Angular Momentum, Torque, and Precession.



### Physics 121. March 27, 2008.

- Course Information
- Quiz
- Topics to be discussed today:
  - Review of Angular Momentum
  - Conservation of Angular Momentum
  - Precession

### Physics 121. March 27, 2008.

- Homework set # 7 is now available and is due on Saturday April 5 at 8.30 am.
- Homework set # 7 has two components:
  - WeBWork (75%)
  - Video analysis (25%)
- Exam # 2 will be graded this weekend and the results will be distributed via email on Monday March 29.
- Make sure you pick up the results of exam # 2 in workshop next week.

### Homework Set # 7.

#### Frank Wolfs

#### Homework Set 07

#### Physics 121, Spring 2008 Due date: 04/05/2008 at 08:30am EDT

This assignment will be counted toward your final grade. You can attempt each problem 50 times; once you exceed this number of attempts, your solutions will not be recorded anymore. You may need to give 4 or 5 significant digits for some (floating point) numerical answers in order to have them accepted by the computer. Note: to use scientific notion, use a notion like xxE+yy. It is important that you use a capital E; answers with a lower case e will be evaluated differently

#### 1. (10 pts) library/type20/prob05.pg

In an Atwood machine, one block has a mass of  $M_1 = 470~g$  and the other has a mass of  $M_2 = 270~g$ . The frictionless pulley has a radius of 4.8~cm. When released from rest, the heavier block moves down 80~cm in 1.95~s (no slippage). What is the magnitude of the acceleration of the lighter block?



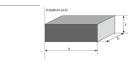
What is the tension  $T_1$ ?

What is the magnitude of the angular acceleration of the pulley?

Find the pulley's moment of inertia.

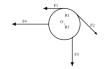
#### 2. (10 pts) library/type20/prob12.pg

The Figure shows a uniform solid 10-kg block. The edge lengths are a=13.4 cm, b=34.8 cm, and c=1.3 cm. What is the rotational inertia about the axis shown in the Figure?



#### 3. (10 pts) library/type20/prob09.pg

A uniform 4.3-kg cylinder can rotate about an axis through its center at 0. The forces applied are:  $F_1 = 4.4 N$ ,  $F_2 = 4.8 N$ ,  $F_3 = 4.2 N$ , and  $F_4 = 2.9 N$ . Also,  $R_1 = 10.6$  cm and  $R_3 = 4.3$  cm. Find the magnitude and direction (+: counterclockwise; -: clockwise) of the angular acceleration of the cylinder.



#### 4. (10 pts) library/type21/prob04.pg

A spherically symmetric object, with radius  $R=0.70\ m$  and mass  $M=1.6\ kg$ , rolls without slipping across a horizontal floor,

with velocity  $V = 1.0 \, m/s$ . It then rolls up an incline with an angle of inclination  $\theta = 45^\circ$  and comes to rest a distance  $d = 2.3 \, m$  up the incline, before reversing direction and rolling back down. Find the moment of inertia of this object about an axis through its context of pages.



#### 5. (10 pts) library/type22/prob02.pg

A gyroscope consists of a rotating uniform disk with a 45-cm radius, suitably mounted at one end of a 10-cm-long axle (of negligible mass) so that the gyroscope can spin and precess freely. Its spin rate is 1493-rev/min. What is the rate of precession if the axle is supported at the other end and is horizontal?

#### 6. (10 pts) library/type21/prob07.pg

A bullet of mass  $m = 0.25 \ kg$  is fired with a velocity of  $v_0 = 81.5 \ m/s$  into a solid cylinder of mass  $M = 21.1 \ kg$  and radius  $R = 0.23 \ m$ . The cylinder is initially at rest and is mounted on a fixed vertical axis that runs through its center of mass. The line of motion of the bullet is perpendicular to the axis and at a distance  $d = 0.0051 \ m$  from the center. Find the angular speed  $\omega$  of the system after the bullet strikes and adheres to the surface of the cylinder.



#### 7. (10 pts) library/type21/prob21.pg

On a frictionless table, a  $0.40 \ kg$  glob of clay strikes a uniform  $1.04 \ kg$  bar perpendicularly at a point  $0.32 \ m$  from the center of the bar and sticks to it. If the bar is  $0.94 \ m$  long and the clay is moving at  $8.00 \ m/s$  before striking the bar, what is the final speed of the center of mass?



#### Rolling Motion.

#### Precession.

Conservation
Of Angular
Momentum.

Conservation
Of Angular
Momentum.

Frank L. H. Wolfs

Pulley problem.

Moment of

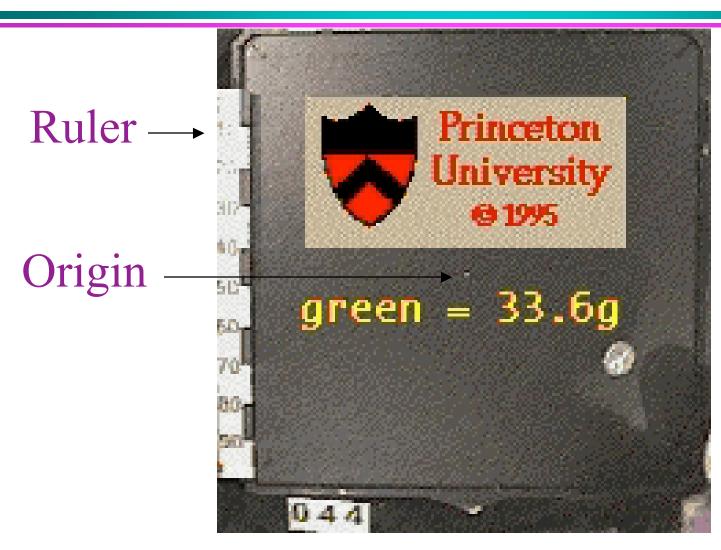
inertia.

**Angular** 

acceleration.

Department of Physics and Astronomy, University of Rochester

# Video analysis. Is angular momentum conserved?

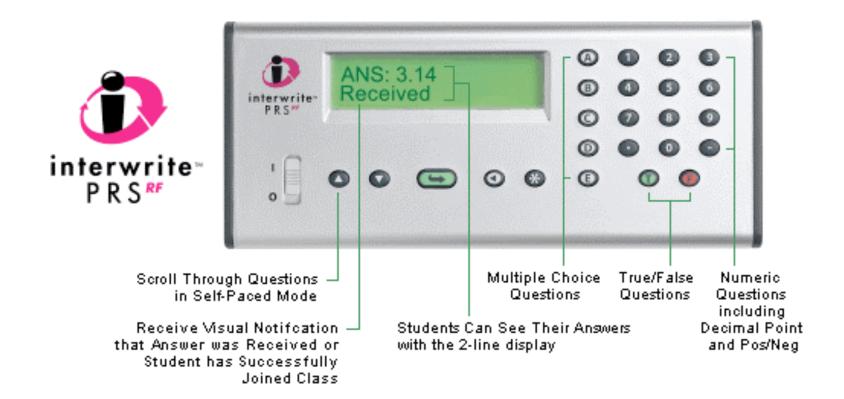


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### Physics 121. Quiz lecture 18.

• The quiz today will have 4 questions!

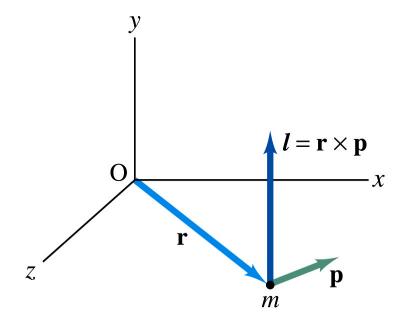


# Angular momentum. A quick review.

- We have seen many similarities between the way in which we describe linear and rotational motion.
- Our treatment of these types of motion are similar if we recognize the following equivalence:

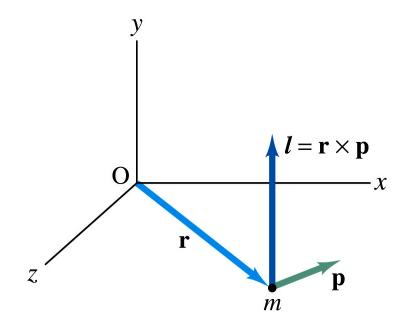
linearrotationalmass mmoment Iforce Ftorque  $\tau = r \times F$ 

• What is the equivalent to linear momentum? Answer: angular momentum.



# Angular momentum. A quick review.

- The angular momentum is defined as the vector product between the position vector and the linear momentum.
- Note:
  - Compare this definition with the definition of the torque.
  - Angular momentum is a vector.
  - The unit of angular momentum is kg m<sup>2</sup>/s.
  - The angular momentum depends on both the magnitude and the direction of the position and linear momentum vectors.
  - Under certain circumstances the angular momentum of a system is conserved!

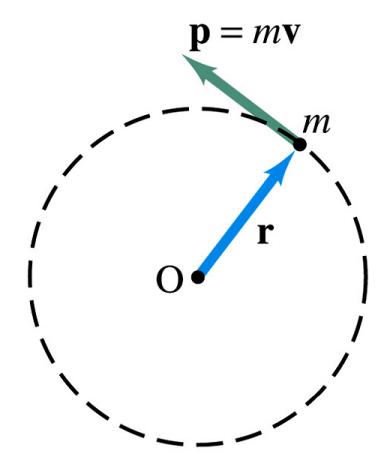


# Angular momentum. A quick review.

- Consider an object carrying out circular motion.
- For this type of motion, the position vector will be perpendicular to the momentum vector.
- The magnitude of the angular momentum is equal to the product of the magnitude of the radius r and the linear momentum p:

$$L = mvr = mr^2(v/r) = I\omega$$

• Note: compare this with p = mv!



# Conservation of angular momentum. A quick review.

• Consider the change in the angular momentum of a particle:

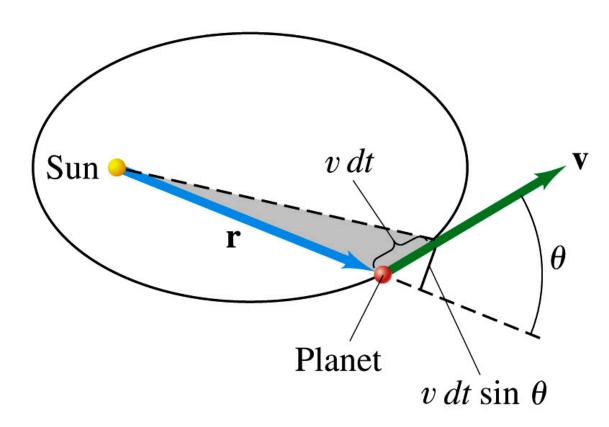
$$\frac{d\vec{\mathbf{L}}}{dt} = \frac{d}{dt}(\vec{\mathbf{r}} \times \vec{\mathbf{p}}) = m\left(\vec{\mathbf{r}} \times \frac{d\vec{\mathbf{v}}}{dt} + \frac{d\vec{\mathbf{r}}}{dt} \times \vec{\mathbf{v}}\right) =$$
$$= m(\vec{\mathbf{r}} \times \vec{\mathbf{a}} + \vec{\mathbf{v}} \times \vec{\mathbf{v}}) = \vec{\mathbf{r}} \times \sum \vec{\mathbf{F}} = \sum \vec{\tau}$$

• Consider what happens when the net torques is equal to 0 Nm:

 $dL/dt = 0 \text{ Nm } \rightarrow L = \text{constant (conservation of angular momentum)}$ 

- When we take the sum of all torques, the torques due to the internal forces cancel and the sum is equal to torque due to all external forces.
- Note: notice again the similarities between linear and rotational motion.

## Conservation of angular momentum. A quick review.



 $L = r mv \sin\theta = m (r v dt \sin\theta)/dt = 2m dA/dt = constant$ 

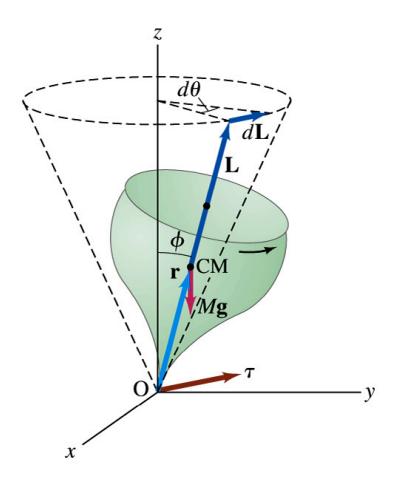
# Conservation of angular momentum. A quick review.

• The connection between the angular momentum L and the torque au

$$\sum \vec{\tau} = \frac{d\vec{L}}{dt}$$

is only true if L and  $\tau$  are calculated with respect to the same reference point (which is at rest in an inertial reference frame).

• The relation is also true if L and  $\tau$  are calculated with respect to the center of mass of the object (note: center of mass can accelerate).

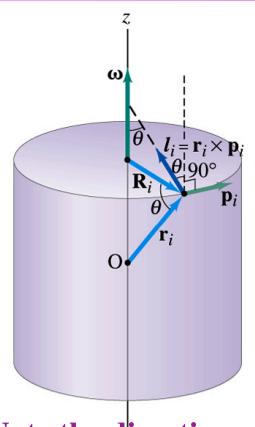


## The angular momentum of rotating rigid objects.

- Consider a rigid object rotating around the z axis.
- The magnitude of the angular momentum of a part of a small section of the object is equal to

$$l_i = r_i (m_i v_i)$$

• Due to the symmetry of the object we expect that the angular momentum of the object will be directed on the z axis. Thus we only need to consider the z component of this angular momentum.



Note the direction of  $l_i$  !!!! (perpendicular to  $r_i$  and  $p_i$ )

## The angular momentum of rotating rigid objects.

• The z component of the angular momentum is

$$L_{i,z} = l_i \sin \theta = (r_i \sin \theta)(m_i v_i) = R_i (m_i v_i)$$

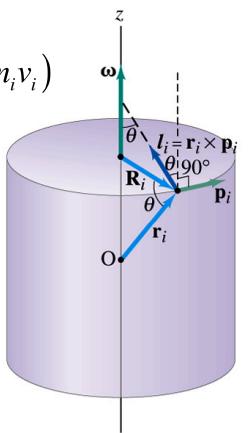
• The total angular momentum of the rotating object is the sum of the angular momenta of the individual components:

$$L_z = \sum L_{i,z} = \sum R_i (m_i v_i) =$$

$$= \sum R_i (m_i \omega R_i) = \omega \sum m_i R_i^2$$

• The total angular momentum is thus equal to

$$L_z = I\omega$$



- The rotational inertia of a collapsing spinning star changes to one-third of its initial value. What is the ratio of the new rotational kinetic energy to the initial rotational kinetic energy?
- When the star collapses, it is compresses, and its moment of inertia decreases. In this particle case, the reduction is a factor of 3:

$$I_f = \frac{1}{3}I_i$$

• The forces responsible for the collapse are internal forces, and angular momentum should thus be conserved.

• The initial kinetic energy of the star can be expressed in terms of its initial angular momentum:

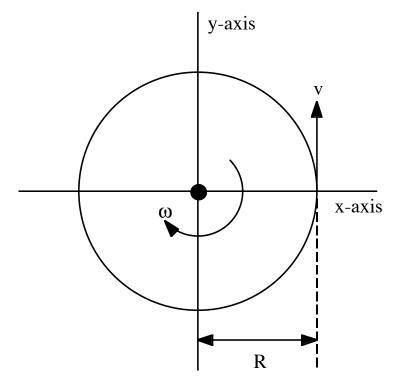
$$K_{i} = \frac{1}{2} I_{i} \omega_{i}^{2} = \frac{1}{2} \frac{L_{i}^{2}}{I_{i}}$$

• The final kinetic energy of the star ca also be expressed in terms of its angular momentum:

$$K_f = \frac{1}{2} \frac{L_f^2}{I_f} = \frac{1}{2} \frac{L_i^2}{\left(\frac{1}{3}I_i\right)} = 3K_i$$

• Note: the kinetic energy increased! Where does this energy come from?

 A cockroach with mass counterclockwise around the rim of a lazy Susan (a circular dish mounted on a vertical axle) of radius R and rotational inertia I with frictionless bearings. The cockroach's speed (with respect to the earth) is v, whereas the lazy Susan turns clockwise with angular speed  $\omega$  ( $\omega$  < 0). cockroach finds a bread crumb on the rim and, of course, stops. (a) What is the angular speed of the lazy Susan after the cockroach stops? (b) Is mechanical energy conserved?



• The initial angular momentum of the cockroach is

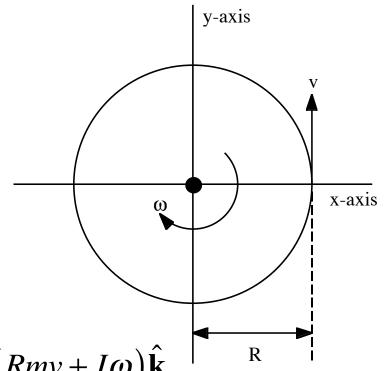
$$\vec{\mathbf{L}}_c = \vec{\mathbf{r}} \times \vec{\mathbf{p}} = Rmv\hat{\mathbf{k}}$$

• The initial angular momentum of the lazy Susan is

$$\vec{\mathbf{L}}_d = I\omega \,\hat{\mathbf{k}}$$

• The total initial angular momentum is thus equal to

$$\vec{\mathbf{L}} = \vec{\mathbf{L}}_c + \vec{\mathbf{L}}_d = Rmv\hat{\mathbf{k}} + I\omega \hat{\mathbf{k}} = (Rmv + I\omega)\hat{\mathbf{k}}$$

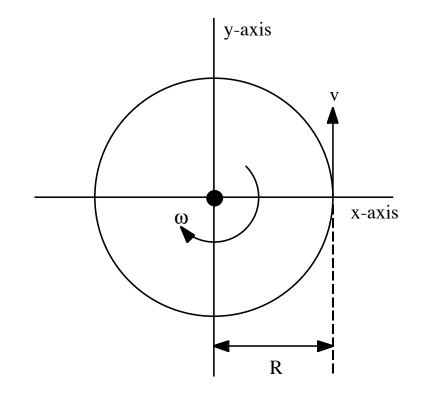


- When the cockroach stops, it will move in the same way as the rim of the lazy Susan. The forces that bring the cockroach to a halt are internal forces, and angular momentum is thus conserved.
- The moment of inertia of the lazy Susan + cockroach is equal to

$$I_f = I + mR^2$$

• The final angular velocity of the system is thus equal to

$$\omega_f = \frac{L_f}{I_f} = \frac{Rmv + I\omega}{I + mR^2}$$



• The initial kinetic energy of the system is equal to

$$K_i = \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2$$

### Cockroach Lazy Susan

• The final kinetic energy of the system is equal to

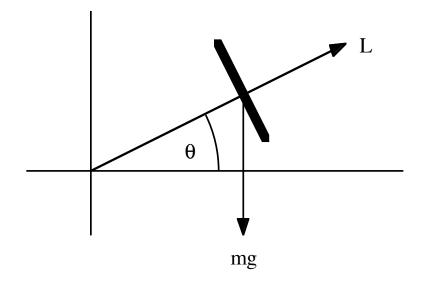
$$K_f = \frac{1}{2}I_f\omega_f^2 = \frac{1}{2}(I + mR^2)\left(\frac{Rmv + I\omega}{I + mR^2}\right)^2 = \frac{1}{2}\frac{(Rmv + I\omega)^2}{I + mR^2}$$

• The change in the kinetic energy is thus equal to

$$\Delta K = K_f - K_i = -\frac{1}{2} \frac{mI}{I + mR^2} (v - R\omega)^2$$

Loss of Kinetic Energy!!

- Consider a rotating rigid object spinning around its symmetry axis.
- The object carries a certain angular momentum L.
- Consider what will happen when the object is balanced on the tip of its axis (which makes an angle  $\theta$  with the horizontal plane).
- The gravitational force, which is an external force, will generate a toques with respect of the tip of the axis.



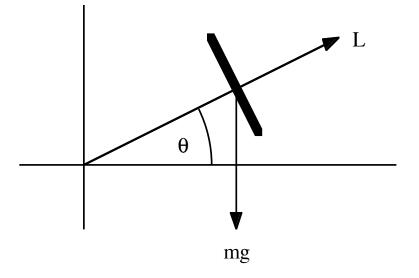
• The external torque is equal to

$$\tau = \left| \vec{\mathbf{r}} \times \vec{\mathbf{F}} \right| = rF \sin \left( \frac{\pi}{2} + \theta \right) = Mgr \cos \theta$$

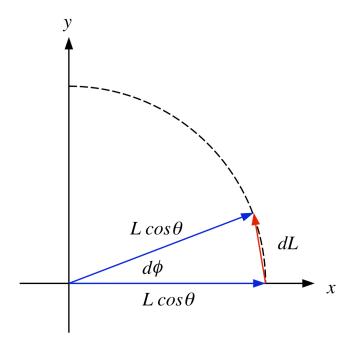
• The external torque causes a change in the angular momentum:

$$d\vec{\mathbf{L}} = \vec{\tau} dt$$

- Thus:
  - The change in the angular momentum points in the same direction as the direction of the torque.
  - The torque will thus change the direction of *L* but not its magnitude.



- The effect of the torque can be visualized by looking at the motion of the projection of the angular momentum in the xy plane.
- The angle of rotation of the projection of the angular momentum vector when the angular momentum changes by dL is equal to



$$d\phi = \frac{dL}{L\cos\theta} = \frac{Mgr\cos\theta dt}{L\cos\theta} = \frac{Mgrdt}{L}$$

• Since the projection of the angular momentum during the time interval dt rotates by an angle  $d\phi$ , we can calculate the rate of precession:

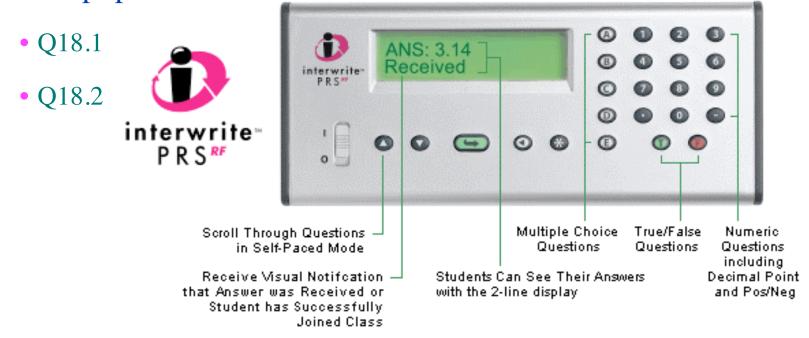
$$\Omega = \frac{d\phi}{dt} = \frac{Mgr}{L} = \frac{Mgr}{I\omega}$$

- We conclude the following:
  - The rate of precessions does not depend on the angle  $\theta$ .
  - The rate of precession decreases when the angular momentum increases.



### Torque and Angular Momentum.

• Let's test our understanding of the basic aspects of torque and angular momentum by working on the following concept problems:



# Done for today! Next week we stop moving and focus on equilibrium.



Spirit Pan from Bonneville Crater's Edge Credit: <u>Mars Exploration Rover Mission</u>, <u>JPL</u>, <u>NASA</u>